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Requirements, Specifications, and Interfaces: Naming Requirements			Revision: 00

Electron-Ion Collider Requirements, Specifications, and Interfaces

# **Naming Requirements**

# October 13, 2023

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#### **REVISION HISTORY**

Revision #	Effective Date	List of Reviewers	Summary of Change
		C. Hetzel, R. Srinivasan,	
		D. Bruno, D. Gassner,	
00	10/12/2022	K. Kulmatycski,	Initial release
00	10/15/2025	J. Jamilkowski, K. Smith,	initial release.
		T. Russo, A. Zaltsman,	
		J. Reich, and K. Wilson	

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#### LIST OF ACRONYMS

BNL	Brookhaven National Laboratory
EIC	Electron-Ion Collider
EPICS	Experimental Physics and Industrial Control System
ESR	Electron Storage Ring
HSR	Hadron Storage Ring
IP	Interaction Point
RHIC	Relativistic Heavy Ion Collider
SBMS	Standards-Based Management System

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# Naming Requirements

## **1. PURPOSE AND SCOPE**

The purpose of this document is to establish the naming conventions for components in the Electron-Ion Collider (EIC) facility. The nomenclature applies to operating devices in the facility that need to have a standard name to support interfaces and controls.

The EIC nomenclature standard defines the syntax and conventions for the naming of components utilized in the facility.

#### 1.1. Role of the Nomenclature Standard

This has been developed based on the principle that it is one of the information domains for devices to be used within the EIC facility. EIC recognizes the importance for "common names" for the development and design of systems and their components.

The role of this nomenclature standard is to provide conventions for the unique naming devices in operation in the facility and to support relation of the information within the other principal information domains for the facility. The syntax has been constructed to work within the rules and limitations of the EPICS (Experimental Physics and Industrial Control System) protocol. With EIC coming online, the control system which actively monitors and controls the devices will utilize EPICS and will follow such syntax.

Being that the Relativistic Heavy Ion Collider (RHIC) did not use EPICS for its duration, many of the systems will not follow this syntax. This nomenclature standard will be the expectation for all devices henceforth.

#### 1.2. Implementation of the Nomenclature Standard

Execution of the standard is delegated to the Group Leaders and their designees who support the daily implementation of the Nomenclature Standard.

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### 2. GENERAL REQUIREMENTS

The format for the nomenclature standard is: Aa bb-ddpp\_nn-cc#

Naming Elements	Description	Requirements
aa	area	from naming bank
bb	specific area	
dd	device	from naming bank
рр	position	
nn	appended number	
сс	controller / signal	from naming bank
#	quantity	

#### 2.1. Area

Naming element as is used to describe the area. The area used depends on the element function. If the element is on the beamline or beamline controlling, the area is defined by the machine prefix and sector. For all other elements, the area is defined by the building name. The area is to be referred to by its abbreviation as assigned in the naming bank [4.1].

Area Type	AA Abbreviation	Description				
Beamline	hs1	Hadron Storage Ring (HSR), sector 1				
Beamline es1		Electron Storage Ring (ESR), sector 1				
Building	1002B	1002B 2 O'clock Cryo Service Building				
Building	1003A	1003A EIC 3 O'clock Power Supply Building				

Examples:

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#### 2.2. Specific Area

Naming element bb is used to describe a specific area. This naming element should only be used when additional location information is beneficial within a building.

Examples:

Area Type	<b>BB</b> Abbreviation	Description
Building	NW	Buildings north wall
Building	R1.1	Building rack row 1 rack 1

#### 2.3. Device

Naming element dd is used to describe the device. The device is referred to by its abbreviation. All abbreviations must come from the naming bank [4.1]

Examples:

DD Abbreviation	Description
bpm	Beam Position Monitor
сс	Cold Cathode Vacuum Gauge
cab	Equipment cabinet
cnb	Conduit bank

#### 2.4. Position

Naming element pp is used to describe the position. The position type used depends on the element function.

#### 2.4.1. Beamline

The position for beamline components is defined by the clock coordinate. The clock coordinate for EIC is based on a virtual circle of circumference 3840m that will lie between the rings to act as a reference s-coordinate. The advantage in this setup is that distance is divisible evenly by 12, allowing us to maintain the clock reference which has been utilized in the past.

Starting at the Interaction Point (IP) of STAR (IP6), distances begin from zero and increase clockwise. The sector/distance naming convention will be sector 6 and goes up from the IP Page 8 of 14

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starting at zero meters and increases up to 320 meters. At that point sector 7 begins, with names starting at 320 and counting down to zero at IP8. This will continue around the machine, creating virtual IP points at 10, 12, 02, and 04.

The distance will be the nearest integer meter to the device or in the case of long devices (ie magnets) it will be to the middle of the device.

#### 2.4.2. Tray

The position for trays is defined by the horizontal location. The lowest tray should start at 1. Numbering should increase as trays are stacked on top.

#### 2.4.3. Equipment cabinets

The position for equipment cabinets is defined by the cabinet row number. The cabinet rows are to start at 1 and increase from north to south / east to west. Free standing cabinets are to be 0.

2.4.4. Wall mounted equipment and conduit banks

The position for wall mounted equipment and conduit banks is to start at 1 and increase from north to south / east to west.

2.4.5. Rack mounted equipment

The position for rack mounted equipment should only be used when applicable. When applicable, the position counting should be determined by the system owner.

#### 2.5. Append number

The element nn is to be used when more than one device type occupying the same position. This naming element should only be used when appropriate. For beamline elements, the append number should increase by clock coordinate. For other elements, the append number should increase from north to south / east to west.

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#### 2.6. Controller / Signal

The element cc is to be used when a controller device or signal type needs to be specified. This is to be referred to by its abbreviation as assigned in the naming bank [4.1].

#### 2.7. Quantity

The naming element # is used for beamline controllers that control more than one beamline component. The element number is the quantity of components it is controlling.

#### **3. EXAMPLES**

#### 3.1. Beamline devices



aa	bb	dd	pp	nn	cc	#	Name	Description
haf		4	40				ha6 d40	HSR dipole 40m before the 6 o'clock
1150		u	40				1150-040	IP
hef		А	40		ng		hs6 d40 ms	HSR dipole power supply 40m before
1150		u	40		ps		1150- <b>u</b> +0-ps	the 6 o'clock IP
256		af	120	2			as 6 af 120 2	ESR focusing quad 130m before 6 o'
650		qı	130	2			eso-q1150_2	clock IP
056		af	120	2	ng		as6 af130.2 m	ESR focusing quad power supply
650		qı	130	2	ps		eso-q1150_2-ps	130m before 6 o' clock IP
es6		ps	130		dcct		es6-ps130-dcct	dcct for es6-qf130_2-ps

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#### **3.2.** Equipment Cabinets

	aa	bb	dd	pp	nn	cc	#	Name	Description
	1009a		cab	1	1			1009a-cab1_1	Row 1 rack 1 in building 1009a
	1009a		cab	2	4			1009a-cab2_4	Row 2 rack 4 in building 1009a



#### 3.3. Conduit Banks

		aa	bb	dd	pp	nn	cc	#	Name	Description
Γ		1009a	nw	cnb	1				1009a nw-cnb1	First conduit bank on 1009a north
									_	wall
	_	1009a	nw	cnh	1	1	de		1009a_nw-cnb1_1-dc	First conduit bank on 1009a north
		10094		Chio	1	1	ue			wall, conduit 1 for DC
		1000a		anh	2				1000a mu anh1	second conduit bank on 1009a
		1009a	пw	cho	2				1009a_nw-ch01	north wall
		1000-		anta	2	6	da		10000 mu onh2 6 oo	second conduit bank on 1009a
		1009a	nw	cno	Z	0	ac		1009a_nw-cnb2_0-ac	north wall, conduit 6 for ac
L		→		•	•					
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#### 3.4. Trays

	aa	bb	dd	pp	nn	cc	#	Name	Description						
_	1000	<b>r</b> 1	tro	1	1	da		1009a_r1-tra1_1-	tray in 1009a, above rack row 1,						
	1009a	11	ua	1	1	uc		dc	bottom level, west tray, for DC						
L	 1000-	1	tro	1	2	2 40		dc	dc	da	da	de		1009a_r1-tra2_1-	tray in 1009a, above rack row 1, second
L	1009a	11	ua	1	2	2 dc				ac	level, west tray, for AC				
L	1000-	<i>"</i> 1	tro	2	2	da		1009a_r1-tra2_2-	tray in 1009a, above rack row 1, second						
L	1009a	r1	tra	Z	Z	ac		lls	level, east tray, for low level signals						
									·						



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#### 3.5. Wall mounted enclosures

1009a ew acp 1 1009a_ew- acp1 ac panel in 1009a, east wall, p one	
acp1 one	position
1000a aw acp 5 1 1009a_ew- ac panel in 1009a, east wall, p	position
acp5 one	



3.6.	<b>Rack devices</b>	(non-beamline)
------	---------------------	----------------

aa	bb	dd	pp	nn	cc	#	Name	Description
1009a	r1.1	blw					1009a_r1.1-blw	1009a rack 1_1 blower
1009a	r2.4	wmf					1009a_r2.4-wmf	1009a rack 2_4 water manifold

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# 4. REFERENCES

#### 4.1. SWN Abbreviation Database